



June, 2024

Research Opportunity

Dear MS program Graduate Students,

We are looking for a master student to work in mobile manipulation for manufacturing in cleanroom. The research task includes

- build simulation environment for mobile manipulation and set up the whole autonomy stack
- Build real world demos using mobile manipulators, e.g., Stretch 3

The position involves all aspects of mobile manipulation: task planning, perception, and position control. The position is for students in CS, ECE or relate departments, who are interested in this area.

If you have interest in this position, please contact us to discuss the details.

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